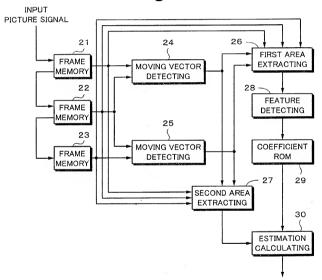


Fig. 6



	f[-1]	f[0]	f[+1]
Fig. 7A	.		()
	- f[-1]	f[0]	f[+1]
Fig. 7B	0 000 00000 000 0	© ©©© ©©●©© ©©© ©	0 000 00000 000 0
Fig. 7C	f[-1] 00000 00000 00000 00000	f[0]	f[+1]
Fig. 7D	f[-1]	f[0]	f[+1] 00000 00000 00000 00000
Fig. 7E	(-1, -1)	(0, 0)	(1, 1)

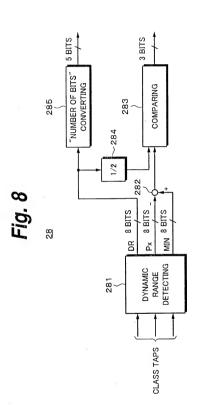


Fig. 9

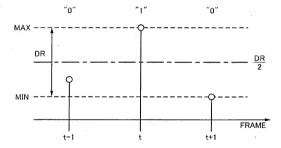


Fig. 10

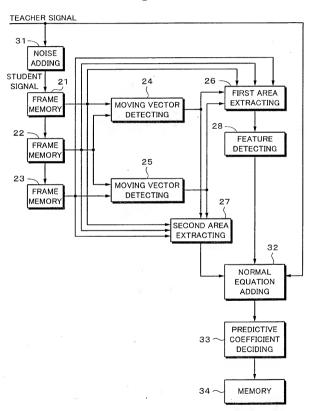


Fig. 11

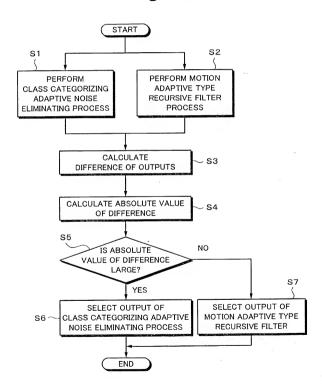


Fig. 12

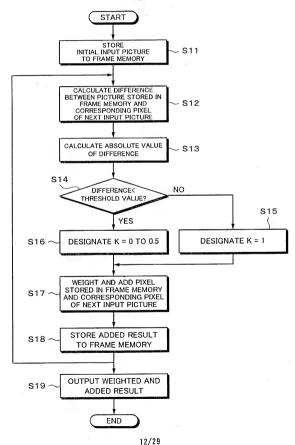
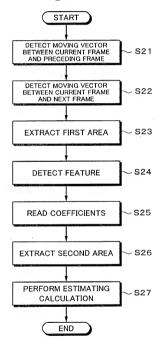
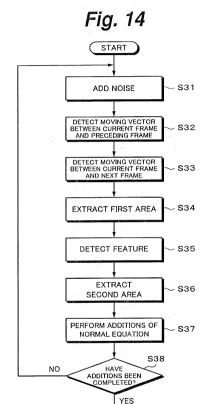


Fig. 13

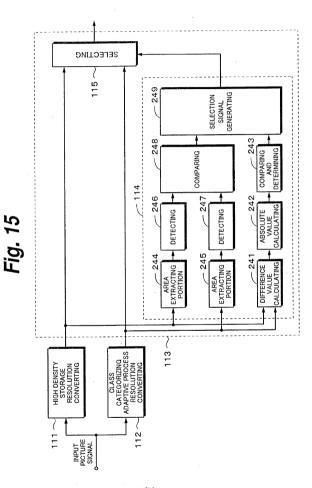




DECIDE PREDICTIVE

COEFFICIENTS

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15/29

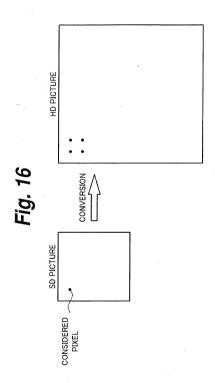


Fig. 17

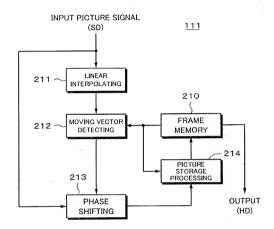
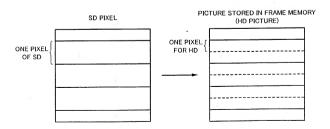


Fig. 18A

Fig. 18B



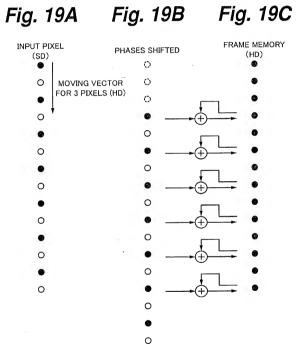
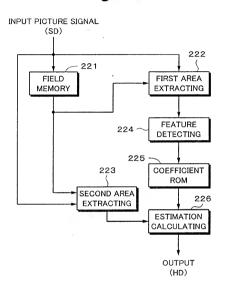
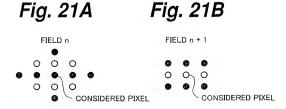


Fig. 20





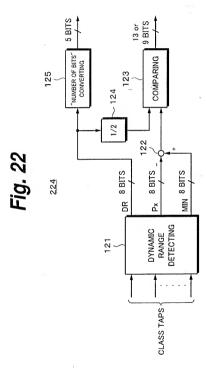


Fig. 23

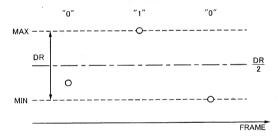


Fig. 24

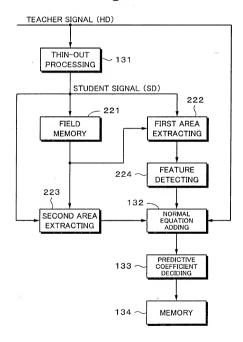


Fig. 25A

NORMAL OUTPUT OF HD

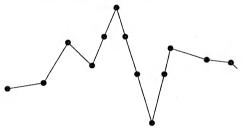


Fig. 25B

OUTPUT OF CLASS CATEGORIZING ADAPTIVE PROCESS

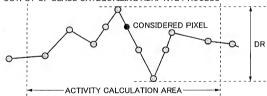
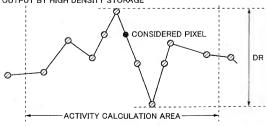
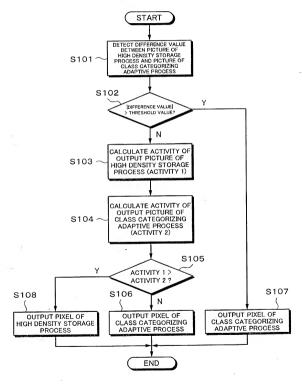


Fig. 25C

OUTPUT BY HIGH DENSITY STORAGE









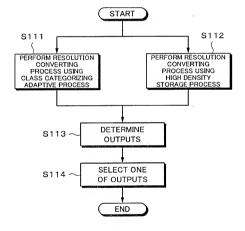
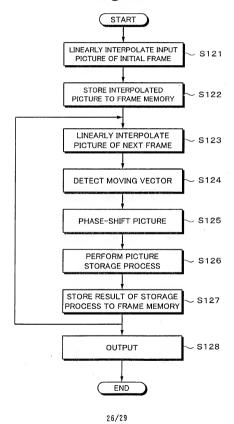


Fig. 28





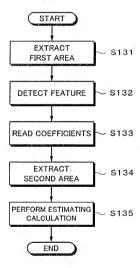
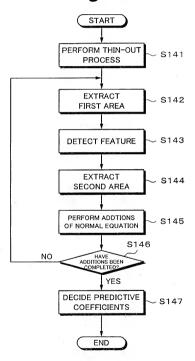


Fig. 30



DESCRIPTION OF REFERENCE NUMERALS

3	FRAME MEMORY
8	WEIGHTING COEFFICIENT GENERATING CIRCUIT
11	MOTION ADAPTIVE TYPE RECURSIVE FILTER
12	CLASS CATEGORIZING ADAPTIVE NOISE ELIMINATING CIRCUIT
13	OUTPUT SELECTING PORTION
14	STILL PORTION - MOVING PORTION DETERMINING CIRCUIT
100	FIRST SIGNAL PROCESSING PORTION
200	SECOND SIGNAL PROCESSING PORTION
111	HIGH DENSITY STORAGE RESOLUTION CONVERTING CIRCUIT
112	CLASS CATEGORIZING ADAPTIVE PROCESS RESOLUTION CONVERTING CIRCUIT
113	OUTPUT SELECTING PORTION
114	DETERMINING CIRCUIT
210	FRAME MEMORY
212	MOVING VECTOR DETECTING PORTION
213	PHASE SHIFTING PORTION